

Benjin Zhu

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Research Interests

My research interests are mainly in computer vision related fields, such as object detection, 3D, and self-supervised learning. I'm looking for a PhD position related to **3D computer vision** or **robotics**.

Education

South China University of Technology

B.Eng. in Software Engineering (**Distinguished Engineer Program**)
First Class Honor with GPA 3.64/4.0

GuangZhou, China
Sep. 2014 – Jul. 2018

Publications

Benjin, Zhu*, Junqiang Huang*, Zeming Li, Xiangyu Zhang, and Jian Sun. **Equivalent Rule for Contrastive Visual Representation Learning**. *in submission*, 2020

Benjin, Zhu, Jianfeng Wang, Zhengkai Jiang, Fuhang Zong, Songtao Liu, Zeming Li, and Jian Sun. **AutoAssign: Differentiable Label Assignment for Dense Object Detection**. *arXiv e-prints: 2007.03496*, 2020

Benjin, Zhu, Zhengkai Jiang, Xiangxin Zhou, Zeming Li, and Gang Yu. **Class-balanced Grouping and Sampling for Point Cloud 3D Object Detection**. *arXiv preprint:1908.09492*, 2019

Ke Xu, Xushen Zheng, Yi Cai, Huaqing Min, Zhen Gao, **Benjin, Zhu**, Haoran Xie, and Tak-Lam Wong. **Improving user recommendation by extracting social topics and interest topics of users in uni-directional social networks**. *Knowledge-Based Systems*, 140:120–133, 2018

Projects

1. **Det3D**: World's first open source 3D object detection framework, with state-of-the art performance on multiple datasets (e.g., nuScenes), based on PyTorch. (**800+ stars**)
2. **cvpack2**: A coherent codebase for many computer vision tasks. cvpack2 is featured by diverse model zoo, flexible experiments management and diverse tasks & datasets support (Classification, Self-supervised Learning, Detection, Segmentation, Keypoint, etc.), based on PyTorch. (**Widely used at megvii research**)

Research Experience

Megvii Research

Researcher (**Full-time**)

Beijing, China
Feb. 2019 – Present

1. 3D Object Detection
 - 1.1 Build world's first open source general 3D Object Detection framework: **Det3D**.
 - 1.2 Winner of the nuScenes 3D Object Detection Challenge in WAD, CVPR 2019.
 - 1.3 Propose a new 3d Object Detection method: **ViP**: View Progressive 3D Object Detection.
2. Object Detection
 - 2.1 Build a multitasking computer vision toolkit **cvpack2**. cvpack2 serves as the unified research framework at Megvii Research.

- 2.2 Propose a novel detector **AutoAssign**, achieving state-of-the-art performance on COCO (52.1% AP).
- 3. Self-supervised Learning
 - 3.1 Research on the training framework of self-supervised contrastive learning. Reproduce many classical CLR models.
 - 3.2 Break the existing cognition about contrastive learning and propose an **equivalent rule for contrastive visual representation learning**. Paper in submission.

DiDi AI Lab

Beijing, China

Research Intern

Jul. 2017 – Nov. 2017

- 1. Using domain adversarial learning to improve CTC's recognition accuracy on multi-source speech datasets.
- 2. Transfer methods in image domain adaptation into speech scenario, decrease recognition error by 1~2%.

Work Experience

Horizon Robotics

Beijing, China

Algorithm Engineer (Full-time)

Apr. 2018 – Feb. 2019

- 1. Setup a full LiDAR 3D Object Detection pipeline from scratch, including data annotation, algorithm design & training, and deploying on FPGA devices.
- 2. Work out a real-time LiDAR sensing demo which was presented in **CES 2019**.

Alibaba Group

Hangzhou, China

Algorithm Engineer (Intern)

Nov. 2017 – Mar. 2018

- 1. Use ODPS(a type of SQL) to perform large scale user activity analysis and video recommendation.
- 2. Feature Engineering using logistic regression, GBDT, DNN, LDA to extract features to perform collaborative filtering.

Honors & Awards

- 2019 **1st Place** of nuScenes 3D Object Detection challenge in WAD, CVPR 2019
- 2019 **3rd Place** of Lyft 3D Object Detection challenge in NeurIPS 2019
- 2018 Honor Graduate
- 2015 – 2017 SCUT School Scholarship

Skills

Programming Languages	Python, C++
Deep Learning Frameworks	PyTorch, MXNet, TensorFlow, MegDL
Backend Frameworks	MongoDB, MPI, CUDA
Languages	English, Chinese, Japanese